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Persistence in high-dimensional linear predictor selection and the virtue of overparametrization

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Let $Z^i = (Y^i, X^i_1, \ldots, X^i_m)$, $i = 1, \ldots, n$, be independent and identically distributed random vectors, $Z^i \sim F$, $F \in \mathcal{F}$. It is desired to predict Y by $\sum \beta_j X_j$, where $(\beta_1, \ldots, \beta_m) \in B^n \subseteq \mathbb{R}^m$, under a prediction loss. Suppose that $m = n^\alpha$, $\alpha > 1$, that is, there are many more explanatory variables than observations. We consider sets B^n restricted by the maximal number of non-zero coefficients of their members, or by their l_1 radius. We study the following asymptotic question: how 'large' may the set B^n be, so that it is still possible to select empirically a predictor whose risk under F is close to that of the best predictor in the set? Sharp bounds for orders of magnitudes are given under various assumptions on $\mathcal{F}$. Algorithmic complexity of the ensuing procedures is also studied. The main message of this paper and the implications of the orders derived are that under various sparsity assumptions on the optimal predictor there is 'asymptotically no harm' in introducing many more explanatory variables than observations. Furthermore, such practice can be beneficial in comparison with a procedure that screens in advance a small subset of explanatory variables. Another main result is that 'lasso' procedures, that is, optimization under l_1 constraints, could be efficient in finding optimal sparse predictors in high dimensions.

Keywords: consistency; lasso; regression; variable selection

1. Introduction

In practice, when modelling statistical phenomena, we tend to adopt more flexible models (e.g., with more parameters) as we obtain more observations. This practice suggests studying the asymptotics of triangular arrays, that is, when the model assumed for the observations $Z^1, \ldots, Z^n$ depends on n. Yet triangular array formulation is hardly ever studied in statistics. The standard mathematical statistical paradigm is the existence of a 'true' model, and the behaviour of estimators is studied as the number of observations increases, while the model is kept fixed. We do not adopt this paradigm. We consider the problem of predictor selection in a given complex situation, and not that of estimation of a metaphysical unknown parameter, which may or may not exist. In fact, the definitions of the predictor and of the parameter are intimately connected. Our parameter of interest is the

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best predictor in a restricted class of potential predictors. A triangular array formulation is natural to our approach.

Consider now the setting of linear predictors in a triangular array. For simplicity, we will denote the observations $Z_n^1, \ldots, Z_n^n$ of a triangular array simply as $Z^1, \ldots, Z^n$. Our study is dedicated to the case where the collection $\mathcal{F}^n$ is a collection of distributions of $(m+1)$-dimensional independent and identically distributed (i.i.d.) vectors $Z^i = (Y^i, X_1^i, \ldots, X_m^i)$, $i = 1, \ldots, n$, where $m = n^\alpha$, $\alpha \geqslant 1$. The set of predictors, that is, the set $\{g_\beta; \beta \in \mathbb{R}^m\}$ of functions of the explanatory variables, is of the form $g_\beta = g_\beta(X_1, \ldots, X_m) = \sum_{i=1}^m \beta_j X_j$, where β ranges over all m-dimensional vectors. Denote

$$L_F(\beta) = \mathrm{E}_F \left(Y - \sum_{j=1}^m \beta_j X_j \right)^2. \tag{1}$$

The set of all possible predictors is too large for estimation. Minimization of the empirical analogue of (1) is essentially unrelated to the minimization of (1) itself. We will search for natural subsets $B^n \subset \mathbb{R}^m$, so that the task of selecting a (nearly) optimal predictor from B^n is not too ambitious, and can be done empirically. It is, of course, desired that those sets will be as large as possible to include better predictors. Finally, the procedures that search for a predictor, that is to say, the 'estimation procedures', should be feasible in terms of their algorithmic complexity.

In our setting a sequence of predictor selection procedures becomes a basic object. Given a set of predictors B^n and a distribution F_n, let $\beta^*_{F_n} = \arg\min_{\beta \in B^n} L_{F_n}(\beta)$.

Definition 1. *Given a sequence of sets of predictors B^n, the sequence of procedures $\hat{\beta}^n$ is called persistent if, for every sequence $F_n \in \mathcal{F}^n$,*

$$L_{F_n}(\hat{\beta}^n) - L_{F_n}(\beta^*_{F_n}) \xrightarrow{\mathrm{p}} 0.$$

Remark 1. In Definition 1 we consider the distance between $L_{F_n}(\hat{\beta}^n)$ and $L_{F_n}(\beta^*_{F_n})$, rather than the more common l_2 distance between $\hat{\beta}^n$ and $\beta^*_{F_n}$. This is the more relevant distance to study in predictor selection. For example, we do not have to worry about collinearity. A consistent estimation of the parameter β is impossible unless we assume that the matrix of the explanatory variables is not close to singularity.

Remark 2. The persistence criterion should have an appeal, in particular, in situations where $L_{F_n}(\beta^*_{F_n})$ does not approach 0. When $L_{F_n}(\beta^*_{F_n})$ might approach 0, a more delicate asymptotic study of rates of convergence, etc., becomes relevant. Yet in most situations and models (nearly) perfect prediction is impossible, thus convergence to 0 of $L_{F_n}(\beta^*_{F_n})$ does not hold.

A study of consistency (in the conventional sense of l_2 distance) in a triangular array setting in regression problems was conducted by Huber (1973) and Portnoy (1984) (see also references therein). They studied the problem of coefficients estimation under the set-up $Y_i = \sum \beta_j X_{ij} + \epsilon_i$, where the ϵ_i are i.i.d., $\mathrm{E}\epsilon_i = 0$, and $m = m(n)$ increases with n. Their

set-up is more conventional than ours since they, unlike us, assume the linear model and study cases where $m(n) < n$. Major differences between our work and theirs are that they were concerned with robustness and M-estimators under heavy-tailed distributions of ϵ_i, unlike us, and we consider random explanatory variables, unlike them. The motivation of these papers seems to be the same as ours: to explore the limits to increasing the parameter set as the number of observations is increased. Yet by their approach, the number of explanatory variables m is taken, as is customary, to be less than n. In fact, it is shown in Huber (1973), under conditions on ϵ_i and the design matrix X, that consistency may be achieved as long as $m(n) = o(\sqrt{n})$. Portnoy, under further conditions, established consistency as long as $m(n) = o(n/\log(n))$. Notice the huge gap!

Given observations $Z^1, \ldots, Z^n$, denote their empirical distribution by $\hat{F}$ and let

$$L_{\hat{F}}(\beta) = n^{-1} \sum_{i=1}^{n} \left(Y^i - \sum_{j=1}^{m} \beta_j X_j^i \right)^2 .$$

Consider predictor selection methods of the following type. For some $c = c(n)$, choose:

$$\hat{\beta}^n = \arg\min_{\beta} L_{\hat{F}}(\beta) + c(n)\|\beta\|_1^2.$$

Here $\|\beta\|_1$ is the l_1 norm of β. A related type of method is: for some $b = b(n)$, let

$$\hat{\beta}^n = \arg\min_{\{\beta : \|\beta\|_1 \leq b(n)\}} L_{\hat{F}}(\beta).$$

These procedures provide the motivation for this paper. They were introduced in Tibshirani (1996), where they were given the name 'lasso'. In that paper a heuristic and numerical study is conducted to find the appropriate $c(n)$ and $b(n)$ for such procedures. In Juditsky and Nemirovski (2000), properties of such procedures with $b(n) \equiv 1$ are studied. Yet the value 1 for $b(n)$ is chosen somewhat arbitrarily. Lee *et al.* (1996) studied similar procedures for estimating parameters in neural networks, and they also concentrated on $b(n) = 1$. In Chen *et al.* (2001), in the context of denoising a signal represented by an overcomplete wavelet system, an analogue of the lasso procedure is suggested; see their equation (5.1). They also discuss the choice of $c(n)$ (choice of λ in their set-up). An overcomplete system defines overparametrization in our terminology.

Two types of sets, $B^n \subset \mathbb{R}^m$, of possible predictors are studied in this paper:

- B^n is the set of all vectors $(\beta_1, \ldots, \beta_m)$ having at most $k = k(n)$ non-zero entries. These are 'model-selection' or 'variable-selection' procedures that choose k explanatory variables from the initial set of m variables. These sets will be denoted B_k^n.
- B^n is the set of all vectors $(\beta_1, \ldots, \beta_m)$ having l_1 norm less than or equal to $b = b(n)$. These sets will be denoted B_b^n.

We will explore the interplay between B_k^n and B_b^n. The first type, 'model selection', is of interest as problems of variable selection have long been studied from various aspects in numerous papers. The second type is of interest because of its relation to lasso methods.

In Section 2 of this paper we will motivate the lasso procedures. We also present an

argument that suggests that the proper values of $c(n)$ and $b(n)$ are $c(n) = o((\log(n)/n)^{1/2})$ and $b(n) = o((n/\log(n))^{1/4})$, respectively. A careful study reveals that, in settings like the multivariate normal, this is not the case. In fact, from the results in Section 4 it follows that, when the Z^i are multivariate normal, the values of $c(n)$ and $b(n)$ should be of the order of $o(\log(n)/n)$ and $o((n/\log(n))^{1/2})$, respectively. In Section 3 we will show persistence with respect to $B^n_{k(n)}$ for $k(n) = o(n/\log(n))$. Optimality of the latter rate is proved, that is, there exist no persistent procedures with respect to sets $B^n_{k(n)}$, when $k(n) = O(n/\log(n))$.

The persistency procedures in Section 3 are algorithmically inefficient: they involve searching over all the subsets of the m explanatory variables of size of order $n/\log(n)$. Additional assumptions, in Section 4, yield persistent and algorithmically efficient procedures with respect to B^n_k for $k(n) = o(n/\log(n))$.

The implications of the study of the above rates are the following. Consider a triangular array. Suppose it is known that $\beta^*_{F_n}$, the (nearly) optimal predictor under F_n, has fewer than $k'(n)$ non-zero coefficients. Alternatively, suppose that it is known that $\|\beta^*_{F_n}\|_1 \leqslant b'(n)$. We will say that the k-sparsity rate and the b-sparsity rate are respectively $k'(n)$ and $b'(n)$. Suppose now that there exist persistent procedures with respect to sets $B^n_{k(n)}$ (sets $B^n_{b(n)}$), where $k(n) > k'(n)$ (where $b(n) > b'(n)$). Then there is 'asymptotically' no virtue in screening in advance smaller subsets of explanatory variables. This follows since the 'persistence rates' $k(n)$ and $b(n)$ imply that by doing so we will not (significantly) improve on procedures that search through the entire set of explanatory variables. Yet obviously, when screening a small subset in advance, we may do harm by dropping potentially important variables.

In practice, persistence rates and sparsity rates are not known. The practical way to act is to test estimators resulting from various assumptions about the persistence rates (e.g., resulting from various constraints $b(n)$ in the lasso procedure) on a test set.

Thus, the importance of our study stems from its suggestion to turn to high dimensions, and its pointing out that often there is 'no harm' in doing so.

In many cases it turns out that persistence rates are $k(n) = o(n/\log(n))$, when $m = n^\alpha$. Such cases are presented in more general prediction problems in work in progress by Greenshtein.

Finally, a practical implication of this paper is its recommendation of the lasso procedure in high dimensions as an effective method to find optimal predictors under sparsity conditions.

2. Motivating and exploring lasso methods

Consider a triangular array, where $Z = (Y, X_1, \ldots, X_{m(n)}) \sim F$, $F \in \mathcal{F}^n$. Denote $X_0 = Y$. We think of Y as a response variable and of X_j as explanatory variables. For any linear predictor associated with a vector $(\beta_1, \ldots, \beta_m)$, denote

$$\gamma' = (-1, \beta_1, \ldots, \beta_m) = (\beta_0, \ldots, \beta_m).$$

Denote

$$L_F(\beta) = \mathrm{E}_F\left(Y - \sum_{j=1}^{m} X_j\beta_j\right)^2$$

$$= \gamma'\Sigma_F\gamma.$$

Here $\Sigma_F = (\sigma_{ij})$, $\sigma_{ij} = \mathrm{E}_F X_i X_j$, $0 \leqslant i, j \leqslant m$.

We think of a sequence of problems where n observations, $Z^1, \ldots, Z^n$, are given and $m = n^\alpha$, $\alpha > 1$. Let $\hat{F}_n$ be the empirical distribution determined by the sample $Z^1, \ldots, Z^n$. Note that

$$L_{\hat{F}_n}(\beta) = \gamma'\Sigma_{\hat{F}_n}\gamma,$$

where $\Sigma_{\hat{F}_n} = (\hat{\sigma}_{ij})$ and $\hat{\sigma}_{ij} = n^{-1}\sum_{k=1}^{n} X_i^k X_j^k$.

Denote $\hat{\sigma}_{ij} = \sigma_{ij} + \epsilon_{ij}^n$; then $\hat{\Sigma} = \Sigma_F + E$, where $E = (\epsilon_{ij}^n)$. Let $Y_{ij} = X_i X_j$. We assume the following condition:

Condition 1. *Under the distributions in $\mathcal{F}^n$, the random variables $Y_{ij} = X_i X_j$ have bounded variances and moment-generating functions with bounded third derivative in the neighbourhood of 0.*

We have, for large enough A, depending on the bounds in Condition 1,

$$\sup_{F_n \in \mathcal{F}^n} P_{F_n}\left(-\sqrt{\frac{A\log(n)}{n}} \leqslant \epsilon_{ij}^n \leqslant \sqrt{\frac{A\log(n)}{n}} \forall i, j\right) \to 1; \tag{2}$$

(2) follows by Bonferroni, since, for large enough A, and for any pair i, j,

$$\sup_{F_n \in \mathcal{F}^n} P_{F_n}\left(-\sqrt{\frac{A\log(n)}{n}} \leqslant \epsilon_{ij}^n \leqslant \sqrt{\frac{A\log(n)}{n}}\right) = 1 - o(m^{-2}),$$

by the moderate deviation principle as in Billingsley (1995, p. 153). The uniformity in $\mathcal{F}^n$ follows from the uniform boundness of the third derivative; such an argument can be seen in Lemma 2.2 of Breiman and Freedman (1983).

Denote by $\hat{E}$ the matrix with identical entries equal to $\sqrt{An^{-1}\log(n)}$. Then (2) implies:

$$\sup_{F_n \in \mathcal{F}^n} P_{F_n}(L_{F_n}(\beta) \leqslant \gamma'\Sigma_{\hat{F}_n}\gamma + |\gamma|'\hat{E}|\gamma| \forall \beta \in R^{m+1}) \to 1, \tag{3}$$

where $|\gamma| = (1, |\beta_1|, \ldots, |\beta_m|)$.

Equation (3) suggests the following method for selecting a predictor. Select the predictor $\hat{\beta}$ where

$$(-1, \hat{\beta}) = \underset{(\gamma \in \mathbb{R}^{m+1}; \beta_0 = -1)}{\arg\min} \gamma'\Sigma_{\hat{F}_n}\gamma + |\gamma|'\hat{E}|\gamma|.$$

Equivalently, write

$$(-1, \hat{\beta}) = \underset{(\gamma \in \mathbb{R}^{m+1}; \beta_0 = -1)}{\arg\min} \gamma' \hat{\Sigma}_F \gamma + c(n) \|\gamma\|_1^2, \tag{4}$$

which may be rephrased as optimization of a convex function in a convex domain. Note that in equation (4), $c(n) = O(\sqrt{\log(n)/n})$.

Here and throughout, we consider procedures that use the appropriate values of $c(n)$, $b(n)$, etc. In practice, the appropriate values are not known, and one should try various values and test the resulting estimators on a test set.

We will now summarize our findings on persistence of procedures of the type

$$\hat{\beta}^n = \underset{\{\beta : \|\beta\|_1 \leq b(n)\}}{\arg\min} L_{\hat{F}}(\beta). \tag{5}$$

Theorem 1. *Under Condition 1 on $\mathcal{F}^n$, for any sequence $B^n_{b(n)} \subset \mathbb{R}^m$, where $B^n_{b(n)}$ consists of all vectors with l_1 norm less than $b(n) = o((n/\log(n))^{1/4})$, there exists a persistent sequence of procedures. A concrete persistent sequence of procedures is given in* (5).

Proof. As in (3),

$$\sup_{F_n \in \mathcal{F}^n} \sup_{\beta \in B^n_{b(n)}} P_{F_n}(|L_{F_n}(\beta) - L_{\hat{F}_n}(\beta)| < |\gamma|' \hat{E} |\gamma|) \to 1.$$

Now, for sequences of vectors β of order $b(n) = o((n/\log(n))^{1/4})$, the corresponding sequence $|\gamma|' \hat{E} |\gamma|$ approaches 0. The result now follows immediately from the definition of persistence. □

Suppose in addition that the following condition holds.

Condition 2. *Let $B^n_{k(n)}$ be the set of all vectors with $k(n) = o((n/\log(n))^{1/2})$ non-zero entries. There exists a constant C, $C < \infty$, such that*

$$\left\| \underset{\beta \in B^n_{k(n)}}{\arg\min} L_{F_n}(\beta) \right\|_2 < C \qquad \text{for any sequence } F_1, F_2, \ldots, F_n \in \mathcal{F}.$$

Remark 3. When $\mathrm{E}_F Y^2$ is bounded, Condition 2 follows whenever the minimal eigenvalue of the covariance matrix of the explanatory variables is bounded from below. As pointed out in Remark 1, assumptions about minimal eigenvalues and near singularity of the random matrix X are essential when dealing with persistence in the conventional sense, that is, when dealing with consistency.

Note that the range of the procedures achieving persistence need not be within the variable selection sets. It is a matter of formalism, but such a requirement was not part of the definition; that is, an estimator $\tilde{\beta}_n$ may be persistent with respect to a set B^n, while $\tilde{\beta}_n \notin B^n$ for some n. We will use this fact in the proof of the following theorem, where sequences with range outside the B^n will be considered. Yet, as shown in Section 4, these procedures may be adjusted so that their range lies within B^n_k.

Theorem 2. *Suppose that Conditions 1 and 2 hold. There exists a persistent sequence of procedures with respect to the sets* $B^n_{k(n)}$ *with* $k(n) = o((n/\log(n))^{1/2})$.

Proof. We consider the particular sequence of procedures which is defined by (5). By Condition 2, we can consider only vectors β with l_2 norm bounded by, say, $C < \infty$. However, any vector with l_2 norm c and of dimension $k(n)$ has l_1 norm less than or equal to $b(n) = c\sqrt{k(n)}$. It follows from Theorem 1 that the estimator defined in (5), with $b(n)$ as above, is persistent with respect to the larger set $B^b_{b(n)}$ hence also for $B^n_{k(n)}$. □

The persistence rate in Theorem 1 is also implied by the following condition, which serves as an alternative to Condition 1.

Condition 3. *There are finite constants* C *and* L *such that, under any* $F \in \mathcal{F}^n$, *for* $n = 1, 2, \ldots,$ $\mathrm{E}_F Y^2 < C$, *and all* $|X_j| < L$ *with probability 1,* $j = 1, \ldots, m(n)$.

Theorem 3. *If Condition 3 holds, then for any sequence* $B^n_{b(n)} \subset \mathbb{R}^m$, *where* $B^n_{b(n)}$ *consists of all vectors with* l_1 *norm less than* $b(n) = o((n/\log(n))^{1/4})$, *there exists a persistent sequence of procedures. A concrete persistent sequence of procedures is given in* (5).

Theorem 3 is implied by an adaptation of the results in Juditsky and Nemirovsky (2000). Condition 3 is close to their set-up. We will now describe their set-up and explain their method and its adaptation to our purpose. We use their notation. Juditsky and Nemirovski study prediction, in a manner similar to ours, of a response variable y, based on a linear combination of given functions $f_1, \ldots, f_M$, where $f_j = f_j(x)$ are functions bounded by some L. They assume a model $y = f(x) + e$, where e and x are independent and $\mathrm{E}(e) = 0$. Given n independent replicates (y_t, x_t), $t = 1, \ldots, n$, they study the problem of estimating the 'best' linear combination of $f_1, \ldots, f_m$ under the constraint that the l_1 norm of the vector of coefficients is 1. 'Best' is understood in terms of the L_2 distance between f and the function obtained by the linear combination. As in our problem, they study asymptotics when $M = n^\alpha$, $\alpha > 1$. This setting is very close to ours when their $f_j(x)$ is identified with our X_j. As demonstrated in what follows, their assumption, concerning the independence of x_t and e_t, is not needed under our definition of persistence. A definition of consistency according to their approach (consistency is not defined in their paper) would involve the L_2 distance between f and the linear combination of f_j. Thus the class we handle in Theorem 3 is slightly larger than the class treated in their set-up.

In what follows we also formulate and prove the conclusion of Theorem 2 under such alternative conditions, stated as Theorem 4. The proofs of Theorems 3 and 4 are along the lines of the technique of Juditsky and Nemirovski.

A statement and a proof of the following key result that is needed later may be found in Emery *et al.* 2000, p. 188).

Lemma 1. (Nemirovski's inequality). *Let* $\xi^t \in \mathbb{R}^K$, $t = 1, \ldots, n$, *be independent random vectors with zero means and finite variance, and* $K \geqslant 3$. *Then, for every* $p \in [2, \infty]$,

$$\mathrm{E}\left\| \sum_{t=1}^{n} \xi^t \right\|_p^2 \leqslant O(1)\min[p, \log(K)] \sum_{t=1}^{n} \mathrm{E}\|\xi^t\|_p^2,$$

where $\|\cdot\|_p$ *is the* l_p *norm.*

We will use the inequality in the case $p = \infty$. There are related results in empirical processes which bound the expectation of the maximum of a finite sequence of random variables. However, we do not yet know of a result that can replace the above inequality in our context.

Consider the matrix $(\Sigma_{\hat{F}} - \Sigma_F)$ as an $(m+1)^2$-dimensional vector. Write $(\Sigma_{\hat{F}} - \Sigma_F)$ as $\sum_{t=1}^{n} \xi^t$, where

$$\xi^t = \frac{1}{n}(X_0^t X_0^t - \mathrm{E}X_0^t X_0^t, X_0^t X_1^t - \mathrm{E}X_0^t X_1^t, \ldots)$$

is an $(m+1)^2$-dimensional vector. Suppose there is an envelope function with respect to $X_i X_j$, $0 \leqslant i, j \leqslant m$, with a bounded second moment, $\mathrm{E}(\max_{i,j} X_i X_j)^2 < \infty$. Then we obtain by Nemirovski's inequality that the expected value of the l_∞ norm of $(\Sigma_{\hat{F}} - \Sigma_F)$ satisfies:

$$\mathrm{E}\left\| \sum \xi^t \right\|_\infty = O\left(\sqrt{\frac{\log(n)}{n}}\right).$$

Now consider B_b^n with $b = b(n) = o((n/\log(n))^{1/4})$. For $\beta \in B_b^n$, by the inequality in Lemma 1 and by Markov's inequality, for $\gamma^t = (-1, \beta_1, \ldots, \beta_m)$ we obtain $|\gamma^t(\Sigma_{\hat{F}_n} - \Sigma_{F_n})\gamma| \xrightarrow{\mathrm{p}} 0$; equivalently, we obtain $|L_{\hat{F}_n}(\beta) - L_{F_n}(\beta)| \xrightarrow{\mathrm{p}} 0$.

Consequently, persistent procedures, relative to sets $B_{b(n)}^n$, of predictors β with l_1 norm less than $b(n) = o((n/\log(n))^{1/4})$ exist. Now, under Condition 2 and by the Cauchy–Schwarz inequality, a persistent selection relative to sets $B_{k(n)}^n$ with $k(n) = o((n/\log(n))^{1/2})$ is also possible.

Remark 4. An envelope function with a second moment for the collection $X_i X_j$, $0 \leqslant i, j \leqslant m$, exists in our triangular array setting if all but a fixed number of X_j, $j = 0, \ldots, m$, are bounded by some L, and all of them have bounded second moment – in particular, when $X_0 \equiv Y$ has a bounded second moment and X_j, $j = 1, \ldots, m$, are bounded as in Theorem 3. Thus Theorem 3 is obtained as a corollary.

The following theorem is obtained from Theorem 3 in the same manner as Theorem 2 follows from Theorem 1.

Theorem 4. *Suppose that the set* $X_i X_j$, $0 \leqslant i, j \leqslant m$, *has an envelope function with a bounded second moment under* $F_n \in \mathcal{F}^n$ $n = 1, 2, \ldots$. *Suppose that Condition 2 holds. Then there exists a method which is persistent with respect to 'variable-selection' sets,* B_k^n, *with* $k(n) = o((n/\log(n))^{1/2})$.

Theorems 2 and 4 are obtained as immediate corollaries of Theorems 1 and 3

respectively, when assuming boundedness of $\|\beta^*_{F_n}\|_2$. With some more effort Theorem 2 may be strengthened and a more flexible condition may replace the one in Theorem 4. In fact, under boundedness of $\|\beta^*_{F_n}\|_2$, a sufficient condition that implies the $k(n) = o((n/\log(n))^{1/2})$ rate is that $\mathrm{E}_{F_n} X_j^{2+\delta}$, $n = 1, 2, \ldots$, $j = 0, \ldots, m(n)$, is bounded for some $\delta > 0$. To show this, one should apply truncation and diagonalization, as in Section 4.

To summarize, we have established the existence of persistent procedures, under various assumptions, when $b(n)$ and $k(n)$ are of orders $o((n/\log(n))^{1/4})$ and $o((n/\log(n))^{1/2})$, respectively. Proofs were based on bounding the l_∞ distance between Σ_F and $\Sigma_{\hat{F}}$.

Later, using different methods, we will explore conditions under which $b(n)$ and $k(n)$ may be 'pushed' towards the rates $o((n/\log(n))^{1/2})$ and $o((n/\log(n)))$, respectively. These rates are optimal in some sense, as will follow below. Compare the huge gap we obtain, under various conditions, for the rates of $k(n)$, with the differences, mentioned in the Introduction, between the rates derived by Huber and those derived by Portnoy.

As mentioned, in work in progress by Greenshtein the $o(n/\log(n))$ rate for $k(n)$ is shown to hold in general triangular arrays, extending linear prediction under a squared prediction loss. However, we do not yet know whether the lower rates, obtained in this section, may be improved even under the elementary assumption that the entries of Z^i are bounded. We state the problem in the following:

1. Consider the case where $\mathcal{F}^n$ consists of all the distributions under which the entries of $Z = (Y, X_1, \ldots, X_m)$ are bounded. Does a procedure exist that is persistent with respect to sets B_b^n, with l_1 radius $b(n)$ which is not $o(n/\log(n))^{1/4}$?
2. Assume that $\mathcal{F}^n$ consists of all distributions under which the entries of Z are bounded. Does a procedure exist which is persistent with respect to sets B_k^n, for $k(n)$ which is not $o(n/\log(n))^{1/2}$?

3. Persistence of model-selection procedures: the normal case

In this section we will study persistence of model-selection procedures, assuming that the sets $\mathcal{F}^n$ consist of multivariate normal distributions. These procedures select at the first stage a model, that is, a subset of $k(n)$ explanatory variables, and then choose a linear predictor based on these variables. The persistence of such procedures is studied with respect to the sets B_k^n that correspond to vectors that have at most $k(n)$ non-zero entries. The question is how far we may push $k(n)$ and still achieve persistence.

Bickel and Levina (2004) study prediction when the explanatory variables are multivariate normal and there are many more explanatory variables than observations. However, they predict the 0–1 variable Y, that is, they study classification in this setting.

Denote the collection of all subsets, of size $k = k(n)$, of explanatory variables by $\mathcal{K} = \mathcal{K}_n$; each of its members is denoted by K, $K \in \mathcal{K}$. Let $\hat{\beta}(K)$ be the least-squares estimator based on the subset K of explanatory variables, and let

$$\hat{\beta} = \arg\min_{K \in \mathcal{K}} L_{\hat{F}}(\hat{\beta}(K)). \tag{6}$$

Similarly, let $\beta^*_F(K)$ be the best linear predictor based on the subset K of the explanatory variables, under F, and $\beta^*_F = \arg\min_{K\in\mathcal{K}} L_F(\beta^*_F(K))$.

The following condition is assumed throughout this section.

Condition 4. *The sets $\mathcal{F}^n$ consist of all multivariate normal distributions with uniformly bounded variance of Y.*

The main result of this section is the following:

Theorem 5. *Suppose $k(n) = o(n/\log(n))$; then there exists a persistent sequence of procedures with respect to the corresponding B^n_k.*

The procedure presented in the proof of Theorem 5 involves searching over all the subsets of size $k(n)$ of the m explanatory variables. In Section 4 we will consider procedures with a lower complexity, which are persistent under a more restricted version of Condition 4.

Before proving the theorem we require the following lemmas and propositions.

Proposition 1. *Suppose $V_n \sim \chi^2_{k_n}$, where $k_n \leqslant \alpha n$, $0 < \alpha < 1$. Then $P(V_n > n) = o(\exp(-\gamma n))$, for some $\gamma > 0$.*

Proof. Since V_n has $\Gamma(k_n/2, 2)$ distribution, its Lebesgue density is given by

$$f(x) = \frac{1}{\Gamma(k_n/2)2^{k_n/2}} x^{k_n/2-1}\mathrm{e}^{-x/2}.$$

In particular, $f(x) = o(1)\mathrm{e}^{-(1-\alpha')x/2}$ on (n, ∞) for any $1 > \alpha' > \alpha - \alpha\log\alpha$. The proposition follows. □

Let $A^\epsilon_n(K)$ be the event $|L_{\hat{F}_n}(\hat{\beta}(K)) - L_{\hat{F}_n}(\beta^*_{F_n}(K))| > \epsilon$, and denote by $B^\epsilon_n(K)$ the event $|L_{\hat{F}_n}(\beta^*_{F_n}(K)) - L_{F_n}(\beta^*_{F_n}(K))| > \epsilon$.

Lemma 2. *There exists $\gamma_1 > 0$ such that for any non-random $K \in \mathcal{K}$,*

$$\sup_{F_n\in\mathcal{F}^n} P_{F_n}(A^\epsilon_n(K) \cup B^\epsilon_n(K)) = o(\exp(-\gamma_1 n)).$$

Proof. The lemma follows from the fact that the probability of both $A^\epsilon_n(K)$ and $B^\epsilon_n(K)$ approaches 0 exponentially fast. For $A^\epsilon_n(K)$ observe that $n \times (L_{\hat{F}_n}(\hat{\beta}(K)) - L_{\hat{F}_n}(\beta^*_{F_n}(K)))$ is distributed as χ^2 with k degrees of freedom and apply Proposition 1. For $B^\epsilon_n(K)$ apply the large-deviation principle for the difference between the random mean and its expectation. □

The number of elements in $\mathcal{K}$ is of order m^k, $k = k(n)$, hence if $m^k \exp(-\gamma_1 n) \to 0$ for some $\gamma_1 > 0$, then we obtain by Bonferroni,

$$\sup_{F_n \in \mathcal{F}^n} P_{F_n}\left(\bigcup_{K \in \mathcal{K}_n} (A_n^c(K) \cup B_n^c(K)) \right) \to 0.$$

If $k(n) = \delta n/\log(n)$ for δ small enough, then $m^k \exp(-\gamma_1 n) \to 0$. Thus we obtain:

Corollary 1. *If* $k(n) = \delta n/\log(n)$, *then for small enough* δ,

$$\sup_{F_n \in \mathcal{F}^n} P_{F_n}(|L_{\hat{F}_n}(\hat{\beta}) - L_{F_n}(\beta^*_{F_n})| > \epsilon) \to 0.$$

Corollary 1 establishes that $L_{\hat{F}_n}(\hat{\beta})$ is a consistent estimator for $L_{F_n}(\beta^*_{F_n})$. It does not, however, imply that, $\hat{\beta}$ is a persistent estimator for $\beta^*_{F_n}$. Recall that for the latter it is necessary that, for every $\epsilon > 0$,

$$\sup_{F_n \in \mathcal{F}^n} P_{F_n}(|L_{F_n}(\hat{\beta}) - L_{F_n}(\beta^*_{F_n})| > \epsilon) \to 0. \tag{7}$$

To obtain (7), and hence to prove Theorem 5, we need the following lemma and its corollary.

Lemma 3. *Suppose* $k(n) = o(n)$. *Then for any fixed* $K \in \mathcal{K}$ *and* $\epsilon > 0$, *there exists* $\gamma > 0$ *such that*

$$\sup_{F_n \in \mathcal{F}^n} P_{F_n}\left(L_{F_n}(\hat{\beta}(K)) - L_{F_n}(\beta^*_{F_n}(K)) > \epsilon \right) = o(\exp(-\gamma n)).$$

Proof. We consider a concrete subset K with indices (say) $1, 2, \ldots, k$, and a concrete F_n. We will omit the index n when there is no ambiguity. Note that for such a concrete subset we may assume, without loss of generality, that

(i) $\beta^*_F(K) = 0$,
(ii) the random variables $X_1, \ldots, X_k$ are i.i.d. $N(0, 1)$.

Assumption (ii) is possible thanks to our definition of persistence in which we consider $L_F(\hat{\beta}) - L_F(\beta^*_F)$ rather than $\|\hat{\beta} - \beta^*_F\|_2^2$, so the problem is invariant under linear transformation of the explanantory variables. Now $L_F(\hat{\beta}(K)) - L_F(\beta^*_F(K)) = \mathrm{E}((W\hat{\beta}(K))^2 | \hat{\beta}(K))$; the random vector W is k-dimensional and consists of i.i.d. $N(0, 1)$ entries which are independent of $\hat{\beta}(K)$; W may be thought of as the explanatory variables in the subset of a future observation. Thus $\mathrm{E}((W\hat{\beta}(K))^2 | \hat{\beta}(K)) = \|\hat{\beta}(K)\|^2$. Let $X(K)$ be the random design matrix, corresponding to the subset of explanatory variables, obtained by the n observations. Then $\hat{\beta}(K) \sim N(0, \sigma_K^2 (X(K)'X(K))^{-1})$; without loss of generality, $\sigma_K^2 = 1$. Hence, $\hat{\beta}'(K)(X(K)'X(K))\hat{\beta}(K) \equiv V \sim \chi^2_{(k)}$. Let λ be the (random) minimal eigenvalue of $X(K)'X(K)$; then $V > \|\hat{\beta}(K)\|^2 \lambda$. Hence,

$$P(\|\hat{\beta}(K)\|^2 > \epsilon) \leqslant P\left(\frac{V}{\lambda} > \epsilon\right) = P\left(\frac{V}{\lambda/n} > \epsilon n\right).$$

Now from Silverstein's (1985) proof of almost sure convergence of the minimal eigenvalue of a Wishart matrix, for any $0 < a < 1$ there exists $\gamma > 0$ such that

$$P\left(\frac{\lambda}{n} < a\right) = o(\exp(-\gamma n)).$$

Also, since $k = o(n)$ and $V \sim \chi^2_{(k)}$ as in Proposition 1 we have

$$P(V > a\epsilon n) = o(\exp(-\gamma n)),$$

for some $\gamma > 0$. Combining the last two equations, we obtain

$$P(\|\hat{\beta}(K)\|^2 > \epsilon) = o(\exp(-\gamma n))$$

for $\gamma > 0$. The proof now follows. □

Corollary 2. *Suppose* $k(n) = o(n/\log(n))$; *then*

$$\sup_{F_n \in \mathcal{F}^n} P_{F_n}\left(\bigcup_{K \in \mathcal{K}} [L_{F_n}(\hat{\beta}^n(K)) - L_{F_n}(\beta^*_{F_n}(K)) > \epsilon]\right) \to 0.$$

Proof of Theorem 5. The proof follows from Corollaries 1 and 2. □

We now show an optimality property of the suggested procedure. It is shown that persistence cannot be achieved under Condition 4 if $k(n)$ is of order $n/\log(n)$.

Theorem 6. *Suppose that* $m = n^\alpha$, $\alpha > 1$. *If* $k(n) > c(n/\log(n))$, $c > 0$, *then there exists no procedure which is persistent with respect to the corresponding* B^n_k.

Proof. We begin by stating Fano's inequality (see Le Cam and Yang 1990, p. 128). Let $K(P, Q)$ be the Kullback–Leibler distance between P and Q and let $J(P, Q) = K(P, Q) + K(Q, P)$. Suppose $X \sim F$, $F \in \{F_1, \ldots, F_M\}$, and $M > 2$; consider the problem of estimating F, based on X, under a 0–1 loss function. Then the minimax risk is at least

$$1 - \frac{1}{\log(M-1)}\left[\log(2) + \frac{1}{2}\max_{i,j} J(F_i, F_j)\right].$$

Let $Z = (Y, X_1, \ldots, X_m)$, where X_i are i.i.d. $N(0, 1)$. For any subset $X_{i_1}, \ldots, X_{i_k}$ of size k, of the explanatory variables, consider the joint distribution of Z determined by $Y = (c_1/\sqrt{k})\sum_{j=1}^k X_{i_j} + \epsilon$; here $\epsilon \sim N(0, 1)$ is independent of X_j, $i = 1, \ldots, m$, and c_1 is a small enough constant properly chosen. Among all subsets of size k, choose M such subsets in the following way. At each stage after choosing a subset, 'delete' all 'neighbouring' subsets having more than $k/2$ common indices with that subset, and then choose the next subset from the remaining ones; keep on selecting subsets according to this procedure until all the subsets of size k are either deleted or chosen. There are M chosen subsets at the end of the process, with M corresponding distributions. Denote the

distributions by $F_1, \ldots, F_M$. Given n i.i.d. observations $Z^1, \ldots, Z^n$, the relevant distributions are the product measures $F_1^{(n)}, \ldots, F_M^{(n)}$. Now note that for the distributions F_i, $i = 1, \ldots, M$, $J(F_i, F_j) = O(1)$, which may be made arbitrarily small by choosing c_1 small enough; thus, $J(F_i^{(n)}, F_j^{(n)}) < c_3 n$, for some c_3 that may be made arbitrarily small when choosing sufficiently small c_1. By construction $L_{F_i}(\beta^*_{F_j}) > L_{F_i}(\beta^*_{F_i}) + c_2$, for a sufficiently small constant c_2 when $i \neq j$.

We now approximate the term $\log(M-1)$ that appears in Fano's inequality. At each stage we delete 'neighbouring' subsets having at least $k/2$ common indices with the subset that was chosen at this stage, until all subsets are either deleted or chosen. The number of subsets of size k is of order m^k. The number of deleted subsets at each stage is of order $n^{\alpha' k}$, $\alpha' < \alpha$. Thus, the number of stages, or, equivalently the number of chosen subsets, M, is

$$M \approx \frac{m^k}{n^{\alpha' k}} \approx n^{(\alpha-\alpha')k} = \exp\left(\log(n)[\alpha - \alpha']\frac{n}{\log(n)}\right).$$

Thus $\log(M) > c_4 n$, for c_4 small enough. Applying Fano's inequality, we obtain the desired result. □

Remark 5. For the case where the explanatory variables are non-random, related results are the 'oracle inequality', Theorem 3 of Donoho and Johnstone (1994), and Lemma A.2 of Foster and George (1994). These results give finer inequalities than needed for the proof of Theorem 6, in the case of orthogonal and non-random explanatory variables.

It seems that these results may be adjusted for our case of random explanatory variables, and yield the conclusion of Theorem 6 even for the case $\alpha = 1$. Yet the main interest in this paper is the case $\alpha > 1$, that is, more explanatory variables than observations. Thus, our relatively simple argument, using Fano's inequality, seems worthwhile. Another advantage of our proof is that it does not rely on normality; it uses general properties of Kullbach–Leibler numbers. Thus, this method of proof indicates that $k(n) = o(n/\log(n))$ cannot be improved in typical situations.

4. Complexity of persistent procedures

The persistent procedure suggested in Section 3 has high complexity. It involves searching through all subsets of the m explanatory variables of size $k(n) = o(n/\log(n))$. Under further restrictions on the triangular array, we will show, in this section, the existence of 'low-complexity' procedures. The complexity of these procedures is essentially the same as that of solving a lasso problem. The lasso method involves optimization of a convex target function subject to convex constraints. Such convex optimization problems have efficient algorithms in general; see Nemirovski and Yudin (1983). For a particular lasso method, an efficient computation algorithm was recently developed by Efron *et al.* (2004).

A key lemma is the following Lemma 4. A proof under a slightly different setting is

given by Juditsky and Nemirovski in their Proposition 2.2, and is attributed to B. Maurey. We give the proof here since we have introduced a slight difference in the formulation, but mainly for completeness' sake.

Lemma 4. *Let* $Z = (Y, X_1, \ldots, X_m)$, $Z \sim F$, *be a random vector. Suppose* $\mathrm{E}_F Y^2 < \infty$; *suppose further that* $|X_j| < c$, $j = 1, \ldots, m$, *with probability 1. Then for any predictor* β *with* l_1 *norm* ν, *there exists a corresponding predictor* β' *such that* β' *has* k *or fewer non-zero entries, and* $L_F(\beta') < L_F(\beta) + c^2\nu^2/k$.

Proof. Assume first that the entries β_j of β are positive. Denote $p_j = \beta_j/\nu$, $j = 1, \ldots, m$. Now consider a randomization of k trials in a multinomial setting with m categories, where the probability of category j is p_j, $j = 1, \ldots, m$. Let $\hat{P}^j$ be the fraction of the k trials whose outcome is in category j, $j = 1, \ldots, m$. Denote $\hat{P} = (\hat{P}_1, \ldots, \hat{P}_m)$. Note that the vector $\hat{P}$ has at most k non-zero entries. We will show that

$$\mathrm{E}_F L_F(\nu\hat{P}) \leqslant L_F(\beta) + \frac{\nu^2 c^2}{k};$$

the proof then follows.

Let $Z = (Y, X_1, \ldots, X_m)$ be independent of $\hat{P}$. In the following the expectation operator E is taken with respect to both $\hat{P}$ and Z:

$$\begin{aligned}
\mathrm{E}L_F(\nu\hat{P}) &= \mathrm{E}\left(Y - \sum \nu\hat{P}_j X_j\right)^2 \\
&= \mathrm{E}\left(Y - \sum \nu p_j X_j + \sum \nu p_j X_j - \sum \nu\hat{P}_j X_j\right)^2 \\
&= \mathrm{E}\left(Y - \sum \nu p_j X_j\right)^2 + \mathrm{E}\left[\sum \nu X_j(p_j - \hat{P}_j)\right]^2 \\
&\quad + 2\mathrm{E}\left(Y - \sum \nu p_j X_j\right)\left(\sum X_j \nu(p_j - \hat{P}_j)\right) \\
&= L_F(\beta) + \mathrm{E}\left[\sum \nu X_j(p_j - \hat{P}_j)\right]^2.
\end{aligned}$$

The last equality follows since $\mathrm{E}(\hat{P}_j - p_j) = 0$ and since $\hat{P}$ and Z are independent. Now note that $\mathrm{cov}(\hat{P}_l, \hat{P}_k) < 0$ for $k \neq l$, to obtain

$$L_F(\beta) + \mathrm{E}\left[\sum \nu X_j (p_j - \hat{P}_j)\right]^2 \leqslant L_F(\beta) + \nu^2 c^2 \sum \mathrm{var}(\hat{P}_j)$$

$$= L_F(\beta) + \nu^2 c^2 \sum \frac{p_j(1-p_j)}{k}$$

$$\leqslant L_F(\beta) + \frac{\nu^2 c^2}{k}.$$

The adaptation of the proof to the case where β_j may also be negative is straightforward. □

Corollary 3. *Let* $Z \sim F$, $\mathrm{E}_F Y^2 < \infty$. *Given* $\epsilon > 0$ *and* β, *let* $c = c(\epsilon)$ *be such that* $|\mathrm{E}_F(Y - \sum \beta_j X_j)^2 - \mathrm{E}_F(Y - \sum \beta_j \tilde{X}_j)^2| < \epsilon$, *where* $\tilde{X}_j = \max\{-c(\epsilon), \min\{X_j, c(\epsilon)\}\}$ *is a truncation of* X_j. *Then there exists a corresponding predictor* β' *such that* β' *has* k *or fewer non-zero entries, and* $L_F(\beta') < L_F(\beta) + \epsilon + c^2 \|\beta\|_1^2 / k$.

For our main result in this section we will assume the following assumption about $\mathcal{F}^n$, which is more restrictive than Condition 4.

Condition 5. *Consider variable selection subsets* B_k^n, *with* $k(n) = o(n/\log(n))$. *Let* κ, $C < \infty$. *Assume, for every* n, *that* $F \in \mathcal{F}^n$ *if and only if* F *is multivariate normal with second moments bounded by* C, *and* $\|\beta_F\|_2 \leqslant \kappa$.

Theorem 7. *Suppose that the* $\mathcal{F}^n$ *satisfy Condition 5. Let* B_k^n *be the set of predictors with* $k(n) = o(n/\log(n))$ *non-zero entries. Then there exists a sequence of procedures* $\beta_n \in B_k^n$, $n = 1, 2, \ldots$, *such that* $\{\beta_n\}$ *is persistent with respect to* B_k^n, *and the numerical complexity of calculating* β_n *is no more than the numerical complexity of the lasso plus an* $O_p(m)$ *term.*

The $O_p(m)$ term in the statement of Theorem 7 comes from extracting a vector β', with $o(n/\log(n))$ non-zero entries, from a vector β obtained by solving a lasso problem. The extraction is in the manner described in the proof of Lemma 3. The strength of Theorem 5, compared with the results in Section 3, is in the lower complexity of the persistent procedures.

Proof. First we will show that, for every $\epsilon > 0$ and n, there exists a $\tilde{\beta}_n = \tilde{\beta}_n(\epsilon)$ such that

$$\sup_{F_n \in \mathcal{F}^n} P_{F_n}(|L_{F_n}(\tilde{\beta}_n) - L_{F_n}(\beta^*_{F_n})| > \epsilon) \to 0,$$

where $\tilde{\beta}_n$ has $o(n/\log(n))$ non-zero coefficients. The result will then follow by a diagonalization argument: $\tilde{\beta}_n(\epsilon_n)$ will satisfy the theorem for $\epsilon_n \to 0$ slowly enough.

For a given ϵ, we will obtain such a $\tilde{\beta} = \tilde{\beta}(\epsilon)$ in a few stages. At the first stage, we obtain $\tilde{\beta}_1$ as follows. Without loss of generality, let $\kappa = 1$ in Condition 5. Let

$$\tilde{\beta}_1 = \underset{\{\beta \,|\|\beta\|_1 \leq \sqrt{k(n)}\}}{\arg\min} L_{\hat{F}}(\beta). \tag{8}$$

Note that by the Cauchy–Schwarz inequality and since $\kappa = 1$, the l_1 norm of β_F^* is less than $\sqrt{k(n)}$, hence

$$L_{\hat{F}_n}(\tilde{\beta}_1) \leqslant L_{\hat{F}_n}(\beta_{F_n}^*). \tag{9}$$

One may check that Corollary 3 may be applied on $\hat{F}_n$ with $\epsilon > 0$ and $c = c_n(\epsilon) = O_p(1)$. Thus we may extract from $\tilde{\beta}_1$ a vector $\tilde{\beta}_1'$, having $k_1 = k_1(n)$ non-zero coefficients that satisfy

$$L_{\hat{F}_n}(\tilde{\beta}_1') \leqslant L_{\hat{F}_n}(\tilde{\beta}_1) + \epsilon + \frac{c^2 k}{k_1}. \tag{10}$$

The extraction is through the multinomial simulation method, described in the proof of Lemma 4.

Choose $k_1(n) = o(n/\log(n))$ satisfying $k(n)/k_1(n) \to 0$. Let $\tilde{\beta}$ be the least-squares estimator, with respect to the subset on which $\tilde{\beta}_1'$ has non-zero coefficients. Since this subset is chosen to be of order $o(n/\log(n))$, we may apply the reasoning and arguments of Section 3 which, together with the above, imply that

$$\sup_{F_n \in \mathcal{F}^n} P_{F_n}(L_{F_n}(\tilde{\beta}) - L_{F_n}(\beta_{F_n}^*) > 2\epsilon) \to 0. \tag{11}$$

The $\tilde{\beta}$ constructed above is not persistent, since (11) should hold for every ϵ. The latter is now easy to achieve using the diagonalization described above. □

5. Concluding remarks

We have demonstrated for the case of multivariate normal Z^i that by increasing the number of explanatory variables from $o(n)$ (for which persistence may be achieved) to n^α, $\alpha > 1$, we can still achieve persistence with respect to all subsets of size $k(n) = o(n/\log(n))$. In cases where there are no clear favourite explanatory variables or a phenomenon has no clear physical interpretation (a 'black box' situation), such a practice merits recommendation. This is especially true since we have demonstrated the existence of algorithmically effective, persistent procedures. In situations more general than the normal case, our results and techniques of proof also indicate that there is almost no loss, but a lot to be gained when increasing the number of explanatory variables. Thus we recommend an inverse of Occam's razor. Occam's razor does not seem relevant for prediction.

The various theorems we have proved show that we may expect persistence for $k(n)$ of an order between $o((n/\log(n))^{1/2})$ and $o(n/\log(n))$. Consequently the l_1 constraint, $b(n)$, in the lasso procedure should be of an order between $o(n/\log(n))^{1/4})$ and $o(n/\log(n))^{1/2})$.

In practice, we do not know what is the right value for $b(n)$. Thus, we might want to use cross-validation in order to try various points in that range. It might even be helpful to try,

through cross-validation, values of $b(n)$ that are larger than those suggested by our theory, for example, values for which there is still a unique solution to the lasso optimization.

Finally, methods that use many more parameters than observations have recently been employed, and the fact that they do not yield poor results due to overfitting is something of a mystery; see Breiman (2001). We have demonstrated that methods that use many more parameters than observations may give good results as long as some restraint is exercised (e.g., optimization under an l_1 constraint). This might give some insight into the mystery of not obtaining poor results due to overfit.

We speculate that in the more general framework of predictor selection from a parametrized set of predictors $\{g_\beta; \beta \in B\}$, under appropriate conditions, empirical minimization subject to l_1 constraints might have good properties, as explored here in the case of linear predictors. This is a subject that is studied in the work in progress mentioned earlier.

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