SPACE -TIME MIXTURE MODELING FOR DISEASE MAPPING

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Session on

Space-Time Modeling of Epidemiological Data

Organized by Andrew Lawson

Overview

- Introduction

- Disease Mapping in Space Using Mixtures

- Disease Mapping in Space and Time

FREQUENT OBJECTIVE IN GEOGRAPHIC EPIDEMIOLOGY

to present that part of the spatial variation of a disease occurrence distribution, which cannot be explained by the different distribution of **known factors** in the various regions nor is due to **random** variation

HOPE: hints to unknown risk factors!

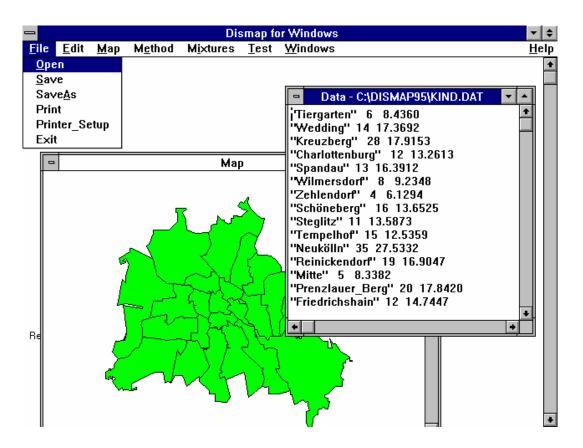
INTRODUCTION

frequently used OCCURRENCE MEASURE in epidemiology and public health institutions

 $SMR_i = O_i/E_i$ in the i-th region

 O_i observed death (mortality) or disease (morbidity) cases

E_i expected cases computed from external reference population



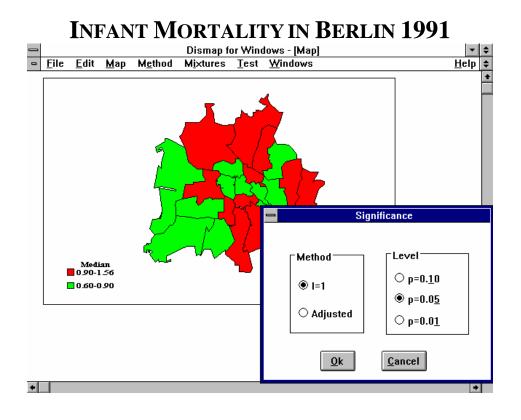
TWO "CLASSIC" BIOMETRIC METHODS

- a) classification based on a certain percentile of the empirical SMR-distribution
- b) Poisson distribution $Po(o_i, \lambda E_i)$

$$= \exp(\lambda E_i) (\lambda E_i)^{O_i} / O_i!$$

classification based on the P-value under the Poissondistribution

 $P(O_i \ge o_i) = Po(o_i, \lambda E_i) + Po(o_i + 1, \lambda E_i) + \dots$

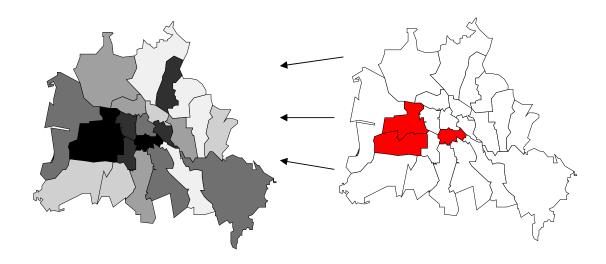


Disadvantage of conventional methods: represent random variation on the map

Disease Mapping in Space using Mixtures

<mark>observed map</mark> of risk structure true, but unobserved map of risk structure (*latent* or *hidden* map)

23 city areas of Berlin



n areas given

<mark>k (unknown)</mark> components: λ₁,...,λ_k

 $O_1, O_2, ..., O_n$ $E_1, E_2, ..., E_n$ $Z_1, Z_2, ..., Z_n$

} observed data
unobserved data

 $\mathbf{Z_i} = (Z_{i1}, ..., Z_{ik})$ with $Z_{ij} = 1$ meaning: area i is from component with risk λ_i

MODEL FOR: $SMR_i = O_i/E_i$ is

 $O_i \sim Po(\lambda_i E_i)$

conditionally O_i is from area with mortality rate λ_i

let p_i probability of being from component with $\lambda = \lambda_i$

then, *unconditionally*

 $O_i \sim p_1 Po(\lambda_1 E_i) + p_2 Po(\lambda_2 E_i) + ... + p_k Po(\lambda_k E_i)$

is a *nonparametric mixture of Poisson* distributions

INTERPRETATION

k= 1: *homogeneous* risk structure k= 2: two risk groups k=3: three risk groups ...

heterogeneous risk structure

maximum likelihood estimation of the parameters $p_1, \lambda_1, ..., p_k, \lambda_k$ inclusively number of components k,

$$\mathbf{P} = \begin{pmatrix} \lambda_1 \ \lambda_2 \ \dots \ \lambda_k \\ p_1 \ p_2 \ \dots \ p_k \end{pmatrix}$$

leads to the *nonparametric maximum likelihood estimate* of a mixing distribution (Laird 1978, Simar 1974, Lindsay 1983, ... Lesperance and Kalbfleisch 1992, Aitkin 1996, ...)

theoretical well-investigated (Lindsay 1995) algorithmically possible (Böhning 1995 *JSPI*)

Map CONSTRUCTION

each area i is classified into component (color) j such that the posterior distribution

$$f(\lambda_j/o_i, E_i, \hat{P}) = Po(o_i, \hat{\lambda}_j E_i) \hat{p}_j / \Sigma_l Po(o_i, \hat{\lambda}_l E_i) \hat{p}_l$$

is maximized !

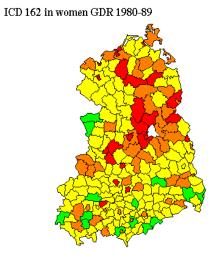
TWO APPLICATIONS

Health Region: 219 counties of the former German Democratic Republic (*The 5 New States of Germany*)

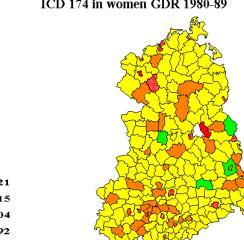
Incidence on Lung Cancer (ICD 162) for Women
 1980–1989

Estimate of Mixing Distribution (NPMLE): $\begin{pmatrix} \lambda_1 \ \lambda_2 \ \dots \ \lambda_k \\ p_1 \ p_2 \ \dots \ p_k \end{pmatrix} = \begin{pmatrix} 1.33 & 0.98 & 0.78 & 0.56 \\ 0.12 & 0.27 & 0.51 & 0.10 \end{pmatrix},$ $\hat{k} = 4$

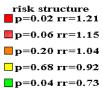
2) Incidence on Mamma-Carcinoma (ICD 174)
- 1980 – 1989



risk structure p=0.12 rr=1.33 **p=0.27 rr=0.98 p=0.51 rr=0.78 p=0.10 rr=0.56**



ICD 174 in women GDR 1980-89



Disease Mapping in Space and Time

n areas given for T periods

IN THE TWO APPLICATIONS

Incidence on Lung Cancer (ICD 162) for Women

- 1980 1989 - 1970 - 1979
- <mark>– 1960 1969</mark>

Incidence on Mamma-Carcinoma (ICD 174)

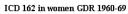
- 1980 - 1989 - 1970 - 1979 - 1960 - 1969

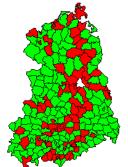
Two Analysis Options

a) $\mathbf{Z_{i}}^{(t)} = (Z_{i1}^{(t)}, ..., Z_{ik}^{(t)})$ with $Z_{ij}^{(t)} = 1$ meaning:

for *each* period: area i is from component with risk $\lambda_j^{(t)}$, j=1,...,k, where k might depend on t

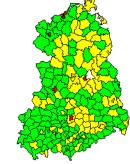
Result: T mixture models, for each time period one: $O_i^{(t)} \sim p_1^{(t)} Po(\lambda_1^{(t)} E_i^{(t)}) + p_2^{(t)} Po(\lambda_2^{(t)} E_i^{(t)}) + \dots + p_k^{(t)} Po(\lambda_k^{(t)} E_i^{(t)})$



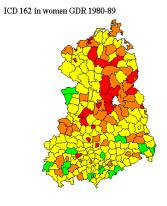


risk structure p=0.38 rr=1.14 p=0.62 rr=0.75

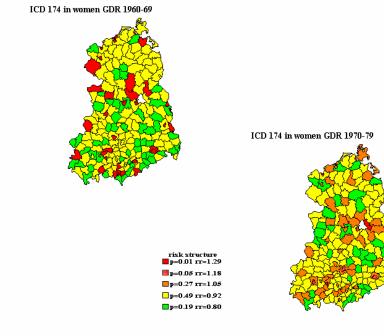


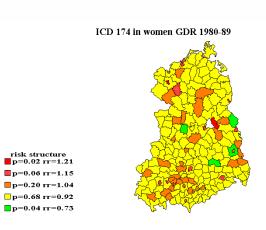


risk structure p=0.06 rr=1 35 p=0.39 rr=1.02 p=0.55 rr=0.71



risk structure p=0.12 rr=1.33 p=0.27 rr=0.98 p=0.51 rr=0.78 p=0.10 rr=0.56





b)
$$\mathbf{Z_{i}^{(t)}} = (Z_{i1}^{(t)}, ..., Z_{ik}^{(t)})$$
 with $Z_{ij}^{(t)} = 1$ meaning:

for *all* periods : area i is from component with risk λ_j , j=1,...,k, where λ_j and k *does not* depend on t

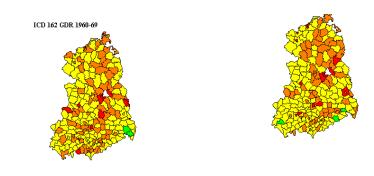
Result: one mixture model

$$O_i^{(t)} \sim p_1 Po(\lambda_1 E_i^{(t)}) + p_2 Po(\lambda_2 E_i^{(t)}) + ... + p_k Po(\lambda_k E_i^{(t)})$$

Note: in *both* cases T maps are drawn, however in a) there are $k^{(1)} + ... + k^{(T)}$ colors b) there are k colors

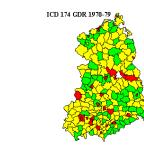
INTERPRETATION:

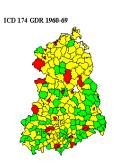
option b) is attractive since it is looking for joint *space-time* components (clusters)



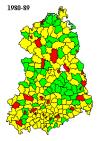
risk structure p=0.10 rr=1.31 p=0.32 rr=1.01 p=0.52 rr=0.76 p=0.06 rr=0.53











Option c)

MORE COMPLEX MIXED MODELING

$$\begin{split} O_{i}^{\,(t)} &\sim p_{1} \, Po \, (\lambda_{i1}^{\,(t)} \, E_{i}^{\,(t)}) + p_{2} \, Po \, (\lambda_{i2}^{\,(t)} \, E_{i}^{\,(t)}) + \\ ...+ p_{k} Po \, (\lambda_{ik} \, E_{i}^{\,(t)}) \end{split}$$

however,

$$log (\lambda_{ij}^{(t)} E_i^{(t)}) = log(E_i^{(t)}) + log(\lambda_{ij}^{(t)})$$

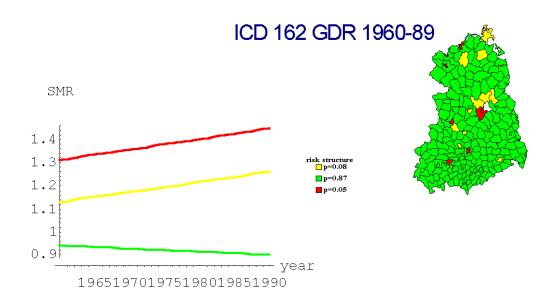
= log(E_i^{(t)}) + \alpha_j + \beta_j t + further covariates

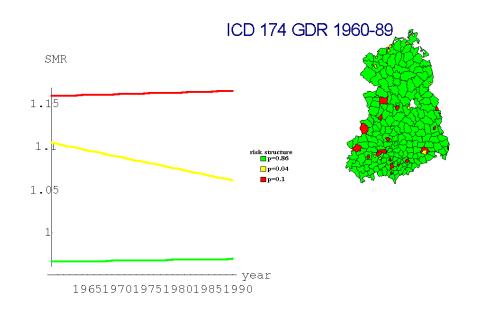
leading to

$$O_i^{(t)} \sim \sum_{j=1}^k p_j \operatorname{Po} \{E_i^{(t)} \exp(\alpha_j + \beta_j t)\}$$

NOTE: in this case the map consists of the k log-linear models (each model one color)

DISADVANTAGE: increased complexity: mixing over intercept or effect parameter? or both?





In Conclusion

- ⇒ investigated possibilities of consistently estimating heterogeneity via nonparametric mixture models
- ⇒ availability of these procedures in C.A.MAN and DISMAP

SOME HINTS TO RECENT REFERENCES

Lawson, Böhning, Biggeri, Lesaffre, Viel, and Bertolini (Eds.), 1998. Disease Mapping and Risk Assessment for Public Health. Wiley & Sons.

Böhning, 1998. *Computer Assisted Analysis of Mixtures and Applications: Disease Mapping, Meta-Analysis and others*. Chapman & Hall